

Address: No.168, Xiadu Road, Haizhu District, Guangzhou, China 510300

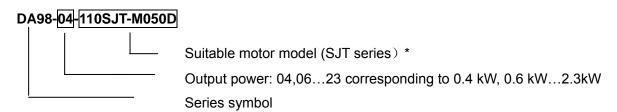
Email: info@CNCmakers.com Website: www.CNCmakers.com Tel: +86-138-24444158 Fax: +86-20-84185336

DA98 SERIES AC SERVO DRIVER

Characteristics:

- With DSP and CPLD, high integration and reliability
- Optimized PID control arithmetic to control motor, increased the veracity and celerity of position and speed
- Mitsubishi IPM, perfect protection, alarm code display, alarm signal output
- Total digital control, user setup of parameters and different display content

Model:









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Specifications:

| MODEL | DA98-10 | DA98-13 | DA98-15 | DA98-23 | DA98-25 | DA98-39 |
|---------------------|---|---------|--|---------|---------|---------|
| Output power (KW) * | 1.0 | 1.3 | 1.5 | 2.3 | 2.5 | 3.9 |
| | 110SJT- | | 110SJT- | | | |
| Suitable motor | M040D | | M060 D | | | |
| (SJT series) | 130SJT- | 130SJT- | 130SJT- | 130SJT- | 130SJT- | 130SJT- |
| | M040 D | M050D | M060 D | M150 B | M100 D | M150 D |
| Input power | Single phase or 3 phases AC 3 phases AC (0.85~1.1) ×220 V | | | | | |
| input power | (0.85~1.1) ×220 V 50Hz/60Hz 50 Hz /60Hz | | | | | |
| Montring | Temperature: working: 0~55℃ storage: -20℃~80℃ | | | | | |
| Working condition | Humidity: less than 90% (no dew) | | | | | |
| Condition | Vibration: less than 0.5G (4.9m/S2), 10Hz~60Hz (no continuous run) | | | | | |
| Control mode | ①position control ② speed control ③ speed dry run ④ JOG run | | | | | |
| Rebirth brake | Inner | | | | | |
| Control | Speed frequency response: not less than 200Hz | | | | | |
| | Speed fluctuation: <± 0.03 (load: 0~100%); <±0.02 (power: -15~+10%) | | | | | |
| characters | (value corresponding to rated speed) | | | | | |
| Cilaracters | Speed ratio: 1:5000 | | | | | |
| | Pulse frequency: ≤500kHz | | | | | |
| | ①servo enable ② alarm release ③ CCW drive forbid ④ CW drive forbid ⑤ warp | | | | | |
| Control input | counter cleanup/ speed select 1 ⑥ dictate pulse forbid/speed select 2 ⑦ CCW torque | | | | | |
| | limit ® CW torque limit | | | | | |
| Control output | ①servo prepared output ② servo alarm output ③ positioned output/ speeded output | | | | | |
| Position control | Input mode | (1 | ①pulse + direction ② CCW pulse/ CW pulse | | | |
| | | ode (3 | ③ 2 phases A/B quadrature pulse | | | |
| | Electric gear ratio 1~32767/1~32767 | | | | | |
| | Feedback pulse 10000 pulse/rotation | | | | | |
| Speed control | 4 kinds inner speed | | | | | |
| Shifting | Parameters setting shifting time: 1ms~10000ms (0r/min-1000r/min) | | | | | |
| function | · · · · · · · · · · · · · · · · · · · | | | | | |
| Monitoring | Rev, current position, dictate pulse accumulate, position warp, motor torque, motor current, linear speed, rotor absolute position, dictate pulse frequency, running state, I/O | | | | | |
| function | terminal signal and so on. | | | | | |
| Protection | | | | | | |
| function | Overspeed, main power overvoltage/ undervoltage, overcurrent, overload, brake | | | | | |
| Display, | abnormity, encoder singularity, control power unconventionality, position warp, etc | | | | | |
| operation | 6bits LED, 4 buttons | | | | | |
| Suitable load | Locathon Etimon of the metade in out | | | | | |
| inertia | Less than 5 times of the motor's inertia | | | | | |
| Weight | 2.8 Kg | | | | | |
| Oversize | 244mmx163mmx92mm (see the figure) | | | | | |
| Oversize | 244mmx roommx92mm (see the figure) | | | | | |